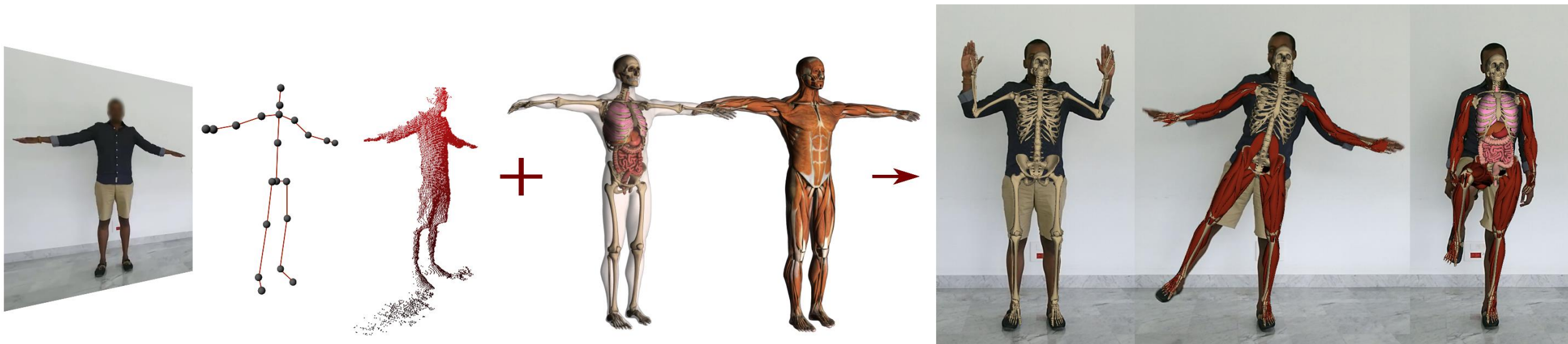


## Anatomical Mirroring: Real-time User-specific Anatomy in Motion Using a Commodity Depth Camera.



Armelle Bauer <sup>2, 3</sup>, Ali-Hamadi Dicko <sup>2, 4</sup>, François Faure <sup>2, 4</sup>, Olivier Palombi <sup>1, 2, 4</sup>, Jocelyne Troccaz <sup>3</sup>

<sup>1</sup> LADAF, <sup>2</sup> LJK, <sup>3</sup> TIMC-IMAG, <sup>4</sup> AnatoScope — **INRIA, CNRS, Univ. Grenoble Alpes**



## Related Work :

- Learning anatomy media
- Using new technologies
- Mirror-like augmented reality (AR)

## Our approach :

- The Living Book of Anatomy (LBA)
- User registration Step
- User tracking Step

## Conclusion

- Results
- Conclusion and future work





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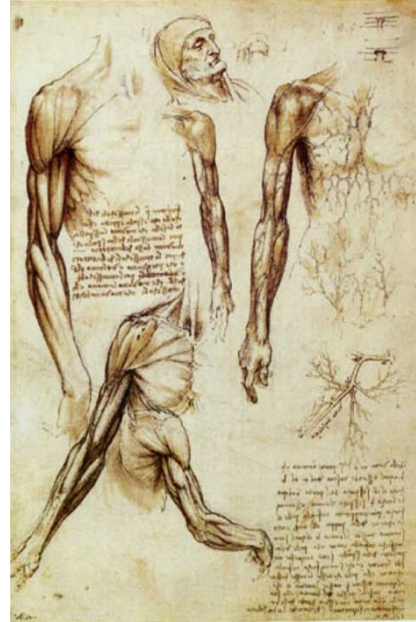
# Motivation : Learning Anatomy

**Anatomy** : static and dynamic structured knowledge

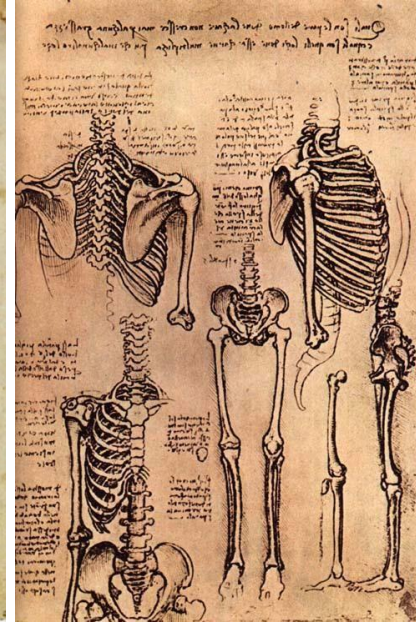
To make the complex task of anatomy learning easier :



**cadaver dissections**



**drawings, books**

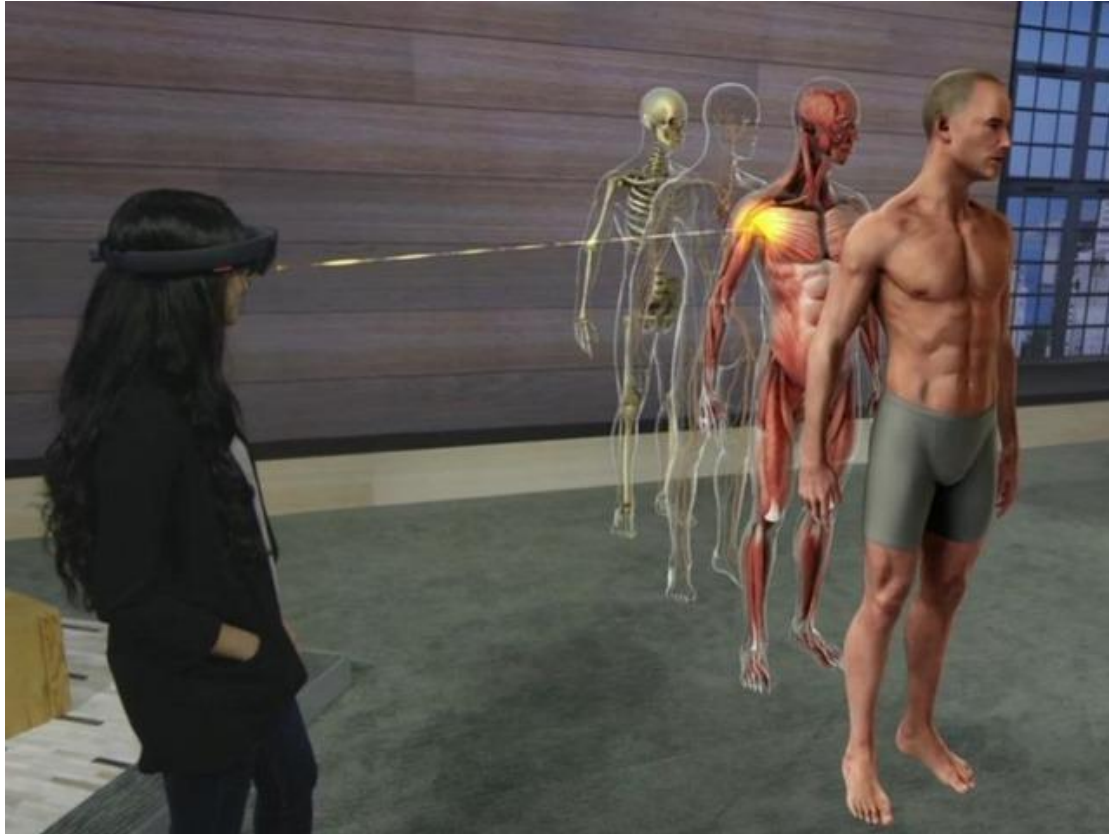


**3D models**

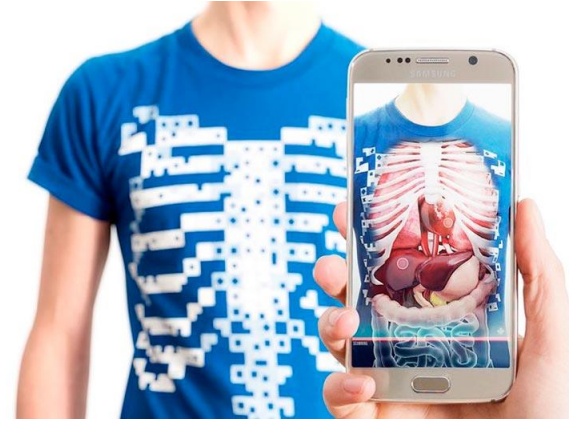
**Learning anatomy for** : medicine students, sports students, general education.



# Mixed reality to learn anatomy



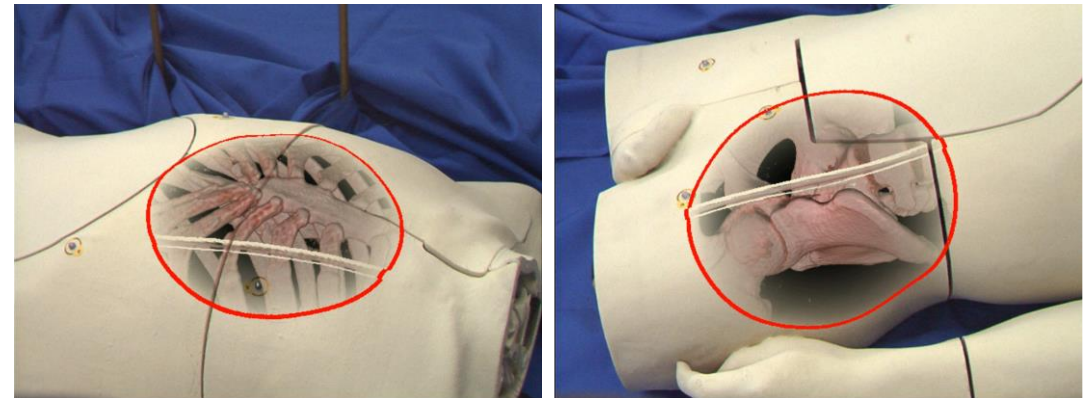
**HoloLens** [Microsoft]



**Virtual-Tee**



**S.A.G.E.** [Anderson & all, 2012]



**Visible Korean human phantom** [Navab 2008]

### Visualization and Interaction with anatomical content displayed onto the user's color map in **real-time** :



**Magic Mirror** [Blum et al, 2012]



**Digital Mirror** [Maître, 2014]



**Anatomie Spiegel** [Borner et al, 2015]

We improve these works by :

- Displaying a **user-specific anatomy** superimposed onto the user's color map.
- Animating the 3D model in **real-time** by maximizing anatomical plausibility.





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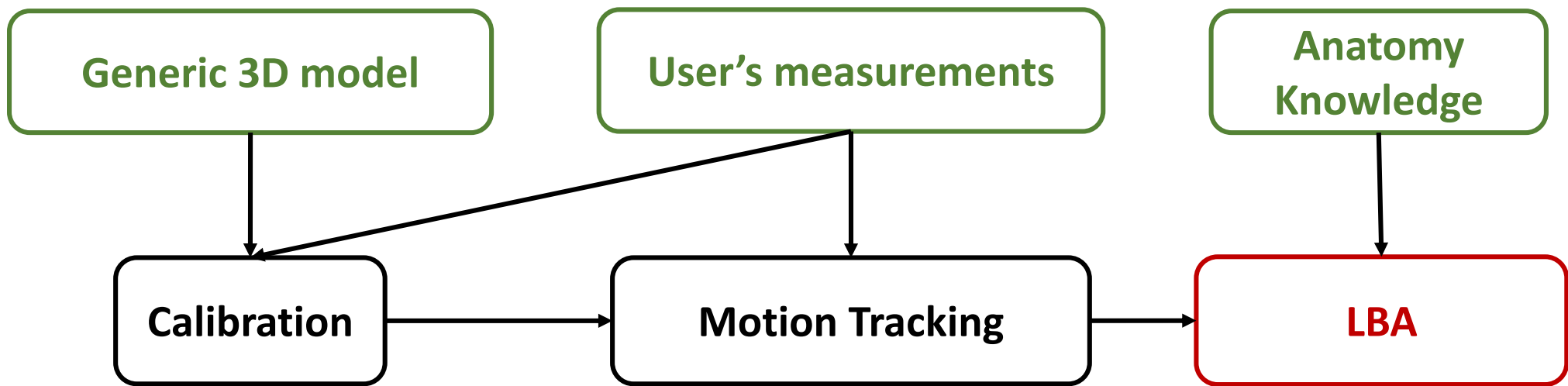
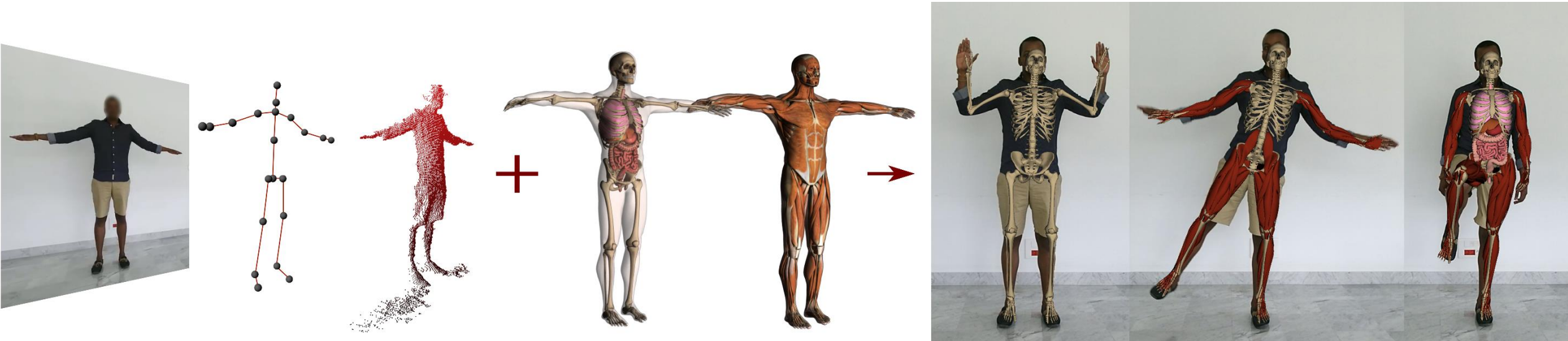
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# Pipeline of our system





## Related Work :

- Learning anatomy media
- Using new technologies
- Mirror-like augmented reality (AR)

## Our approach :

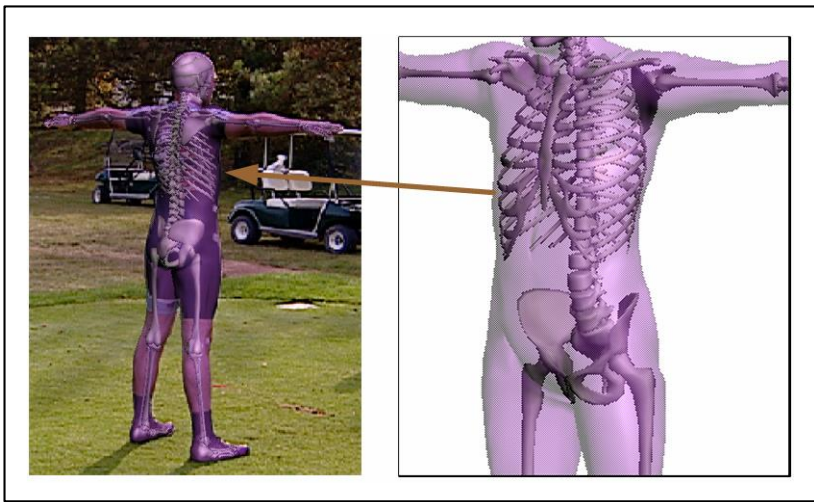
- The Living Book of Anatomy (LBA)
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## Conclusion

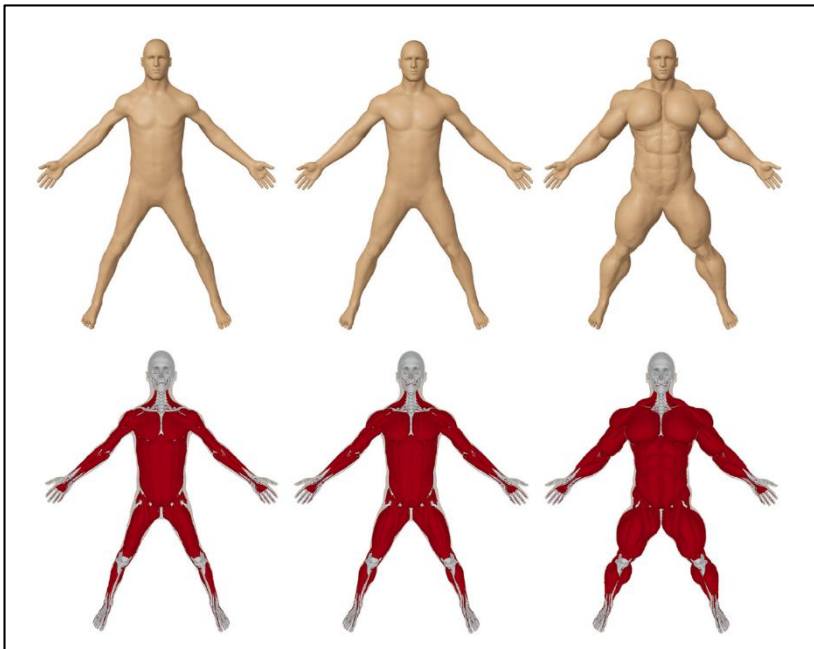
- Results
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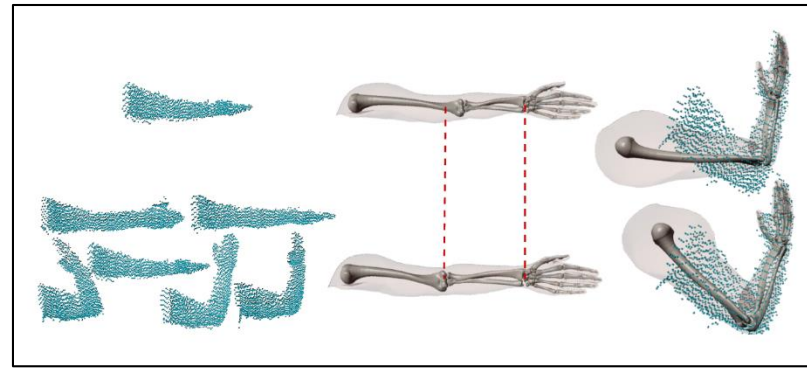
# Anatomy registration : state of the art



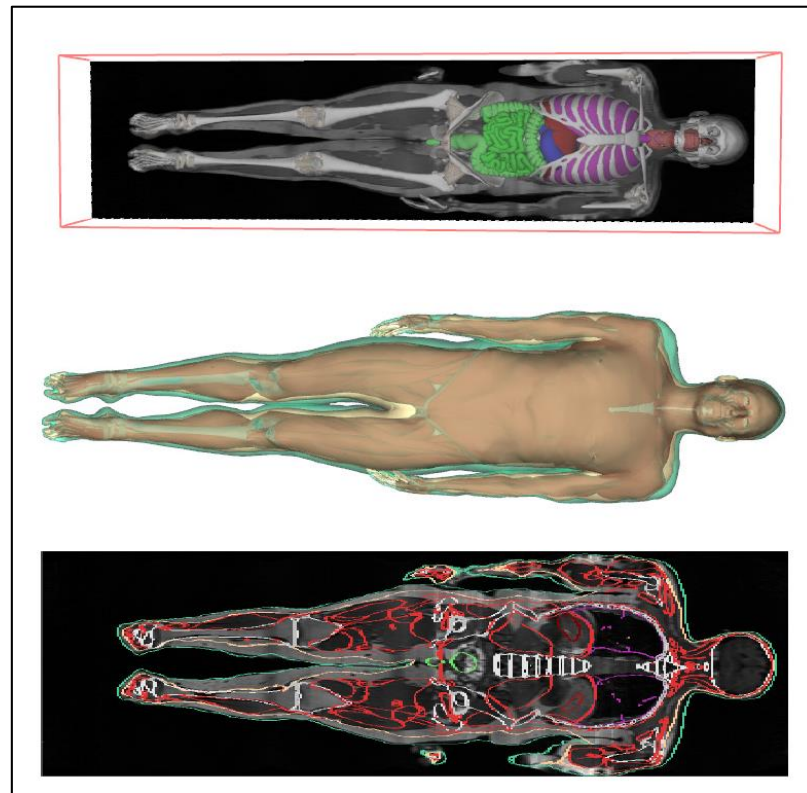
> Quah et al [2005]



> Saito et al [2015]

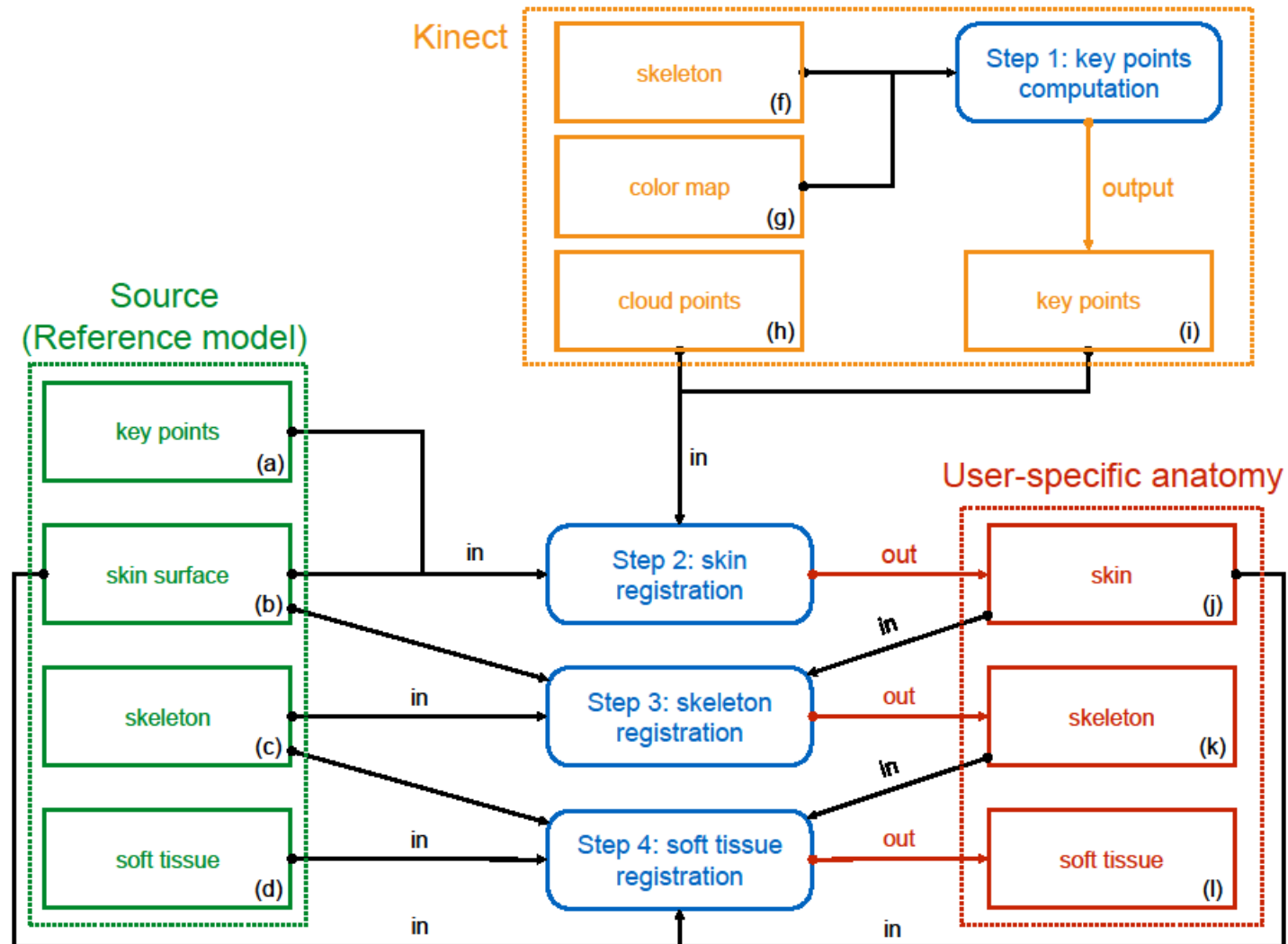


> Zhu et al [2015]



> Dicko et al [2014]

# Our method : registration pipeline



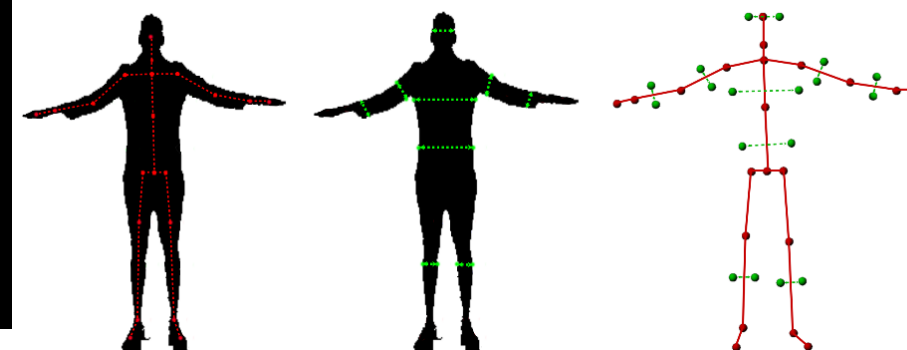
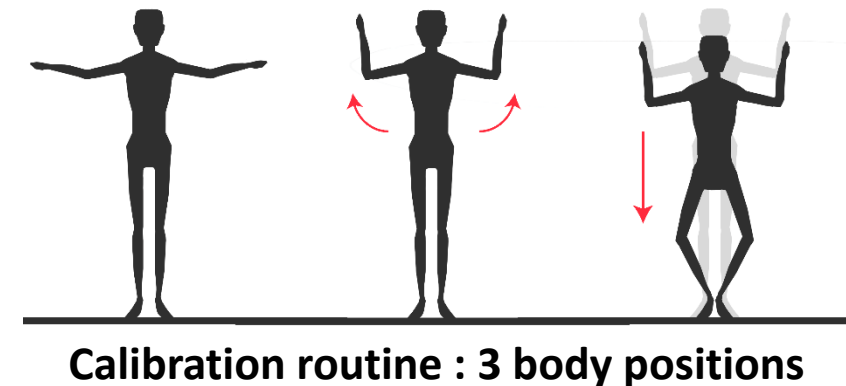
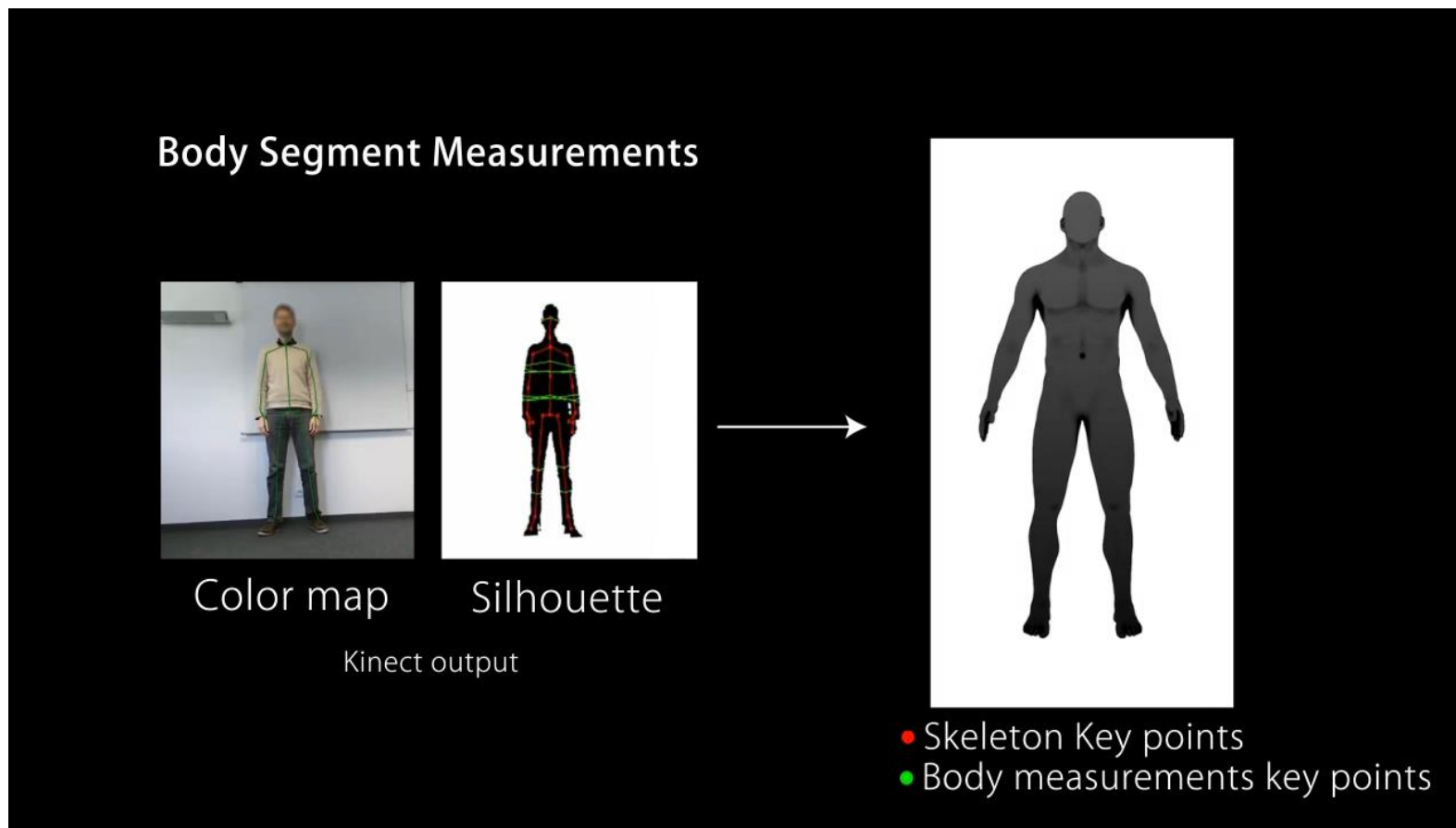
## Anatomy Transfer

Ali-Hamadi Dicko, Tiantian Liu, Benjamin Gilles, Ladislav Kavan, François Faure, Olivier Palombi, Marie-Paule Cani  
ACM Transactions on Graphics (TOG), 2013

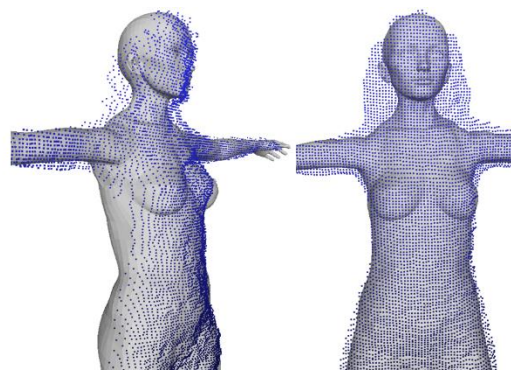
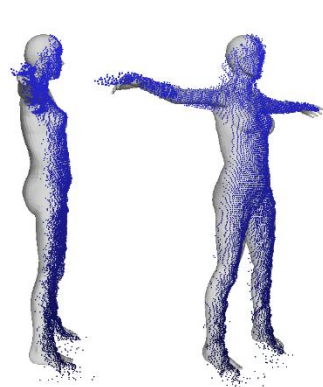
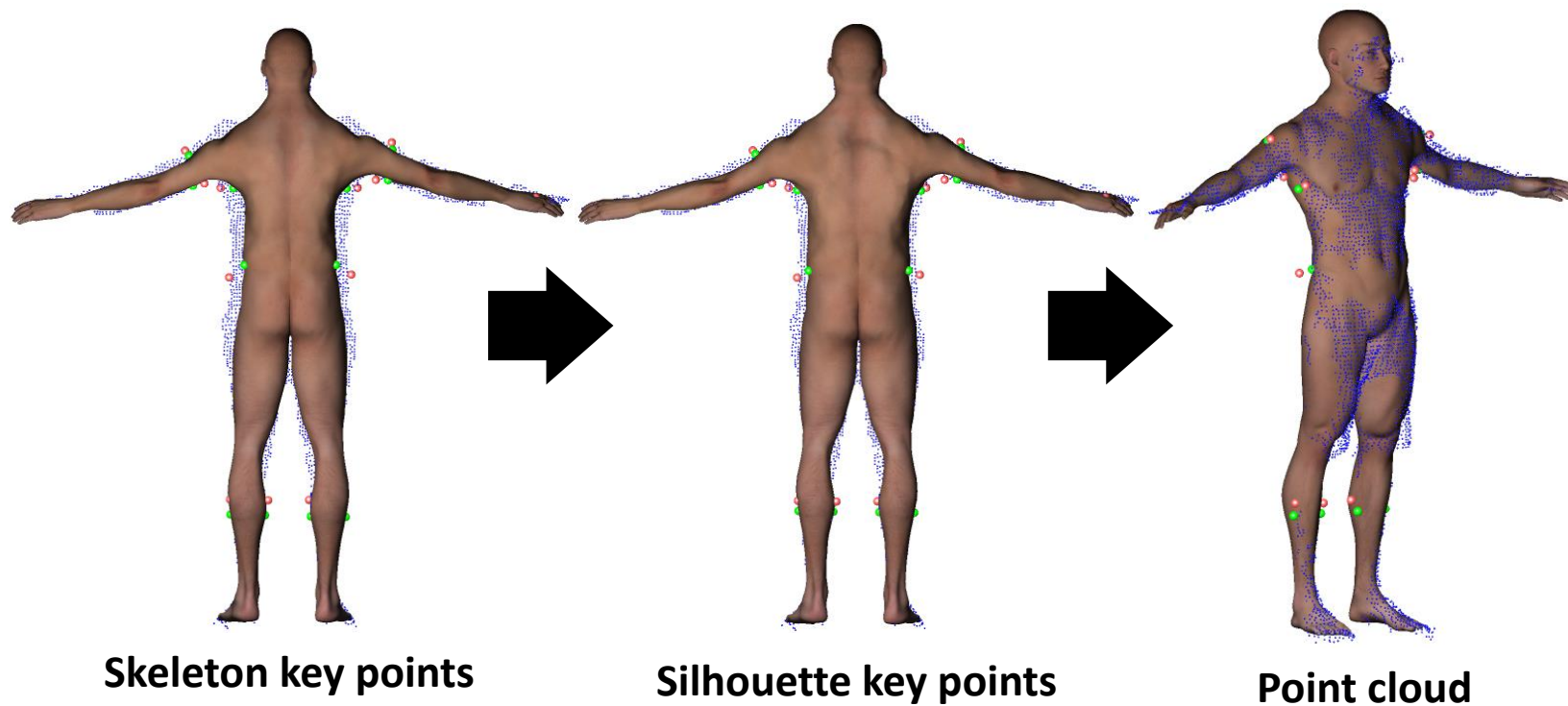


## Step 1 : key points computation

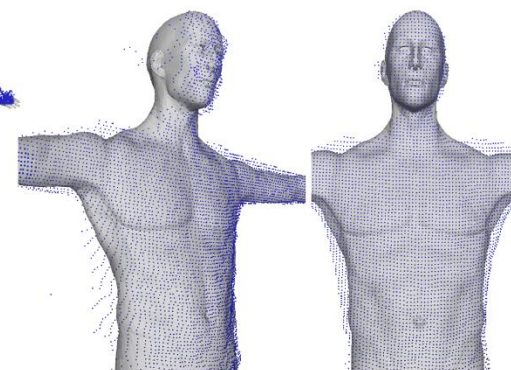
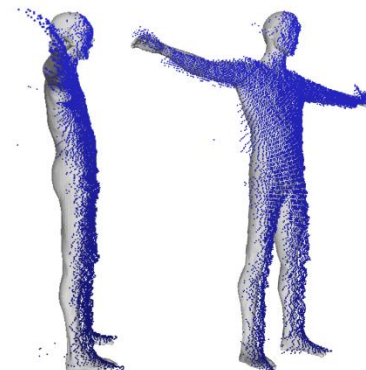
Key points are used to define body **joint positions** and **body measurements** for skin registration.



## Step 2 : skin registration



*> female 1,55m*



*> male 1,85m*



## Step 3 : skeleton registration

### Anatomy Consistency rules:

- **R01:** Keep long bones straightness (*no bending or twisting*)
- **R02:** Keep 3D model consistency: the complete set of entities is transferred to avoid holes
- **R03:** Keep bone head consistency
- **R04:** Keep consistency of rib cage and limbs: symmetry with respect to the sagittal plane
- **R05:** Keep body joints consistency: type of joint and movement amplitude

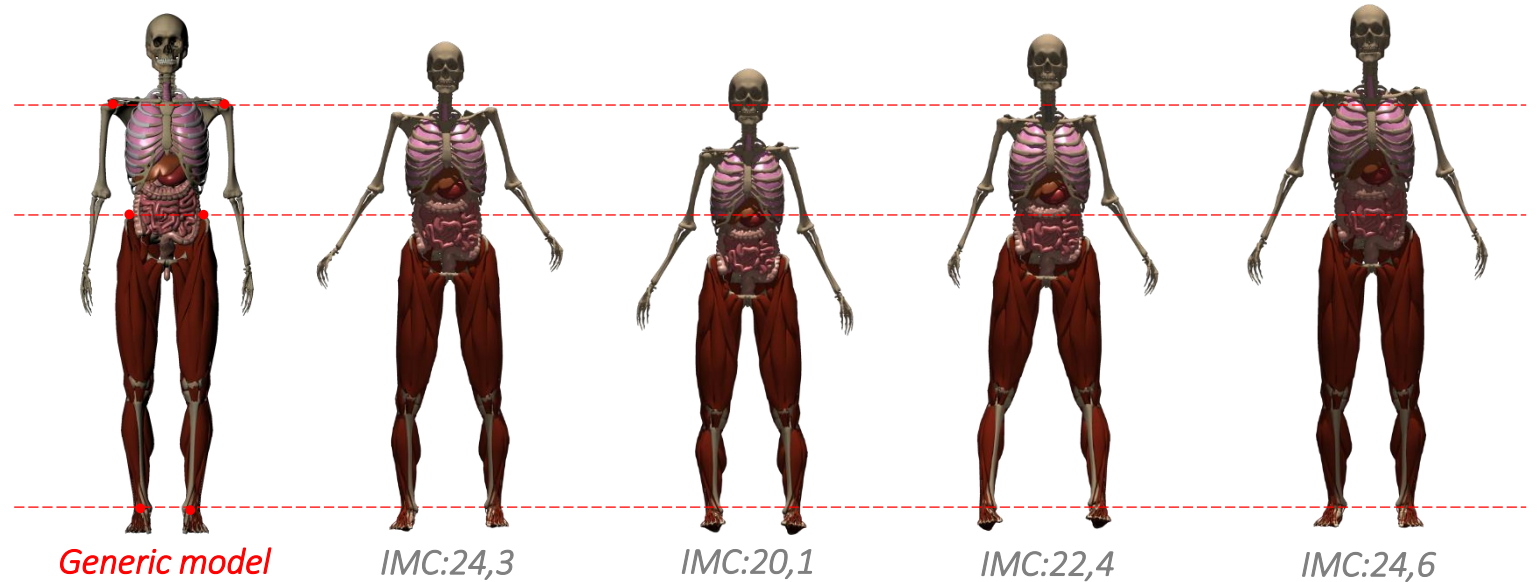
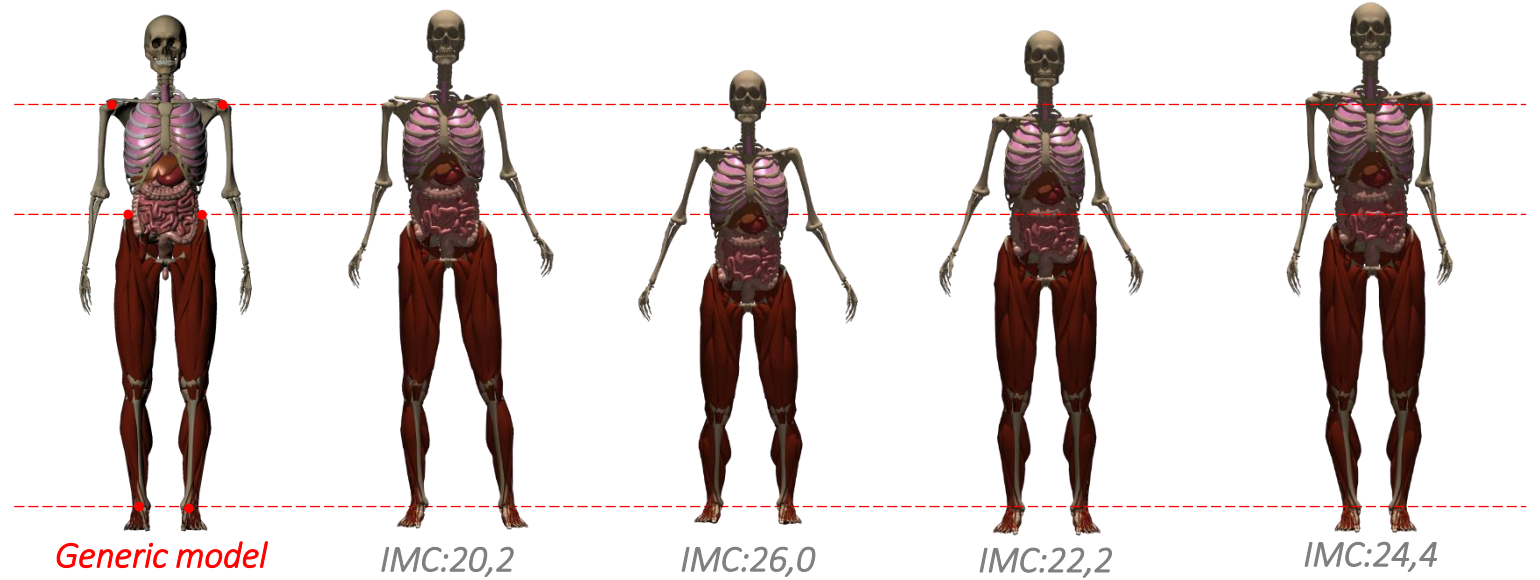
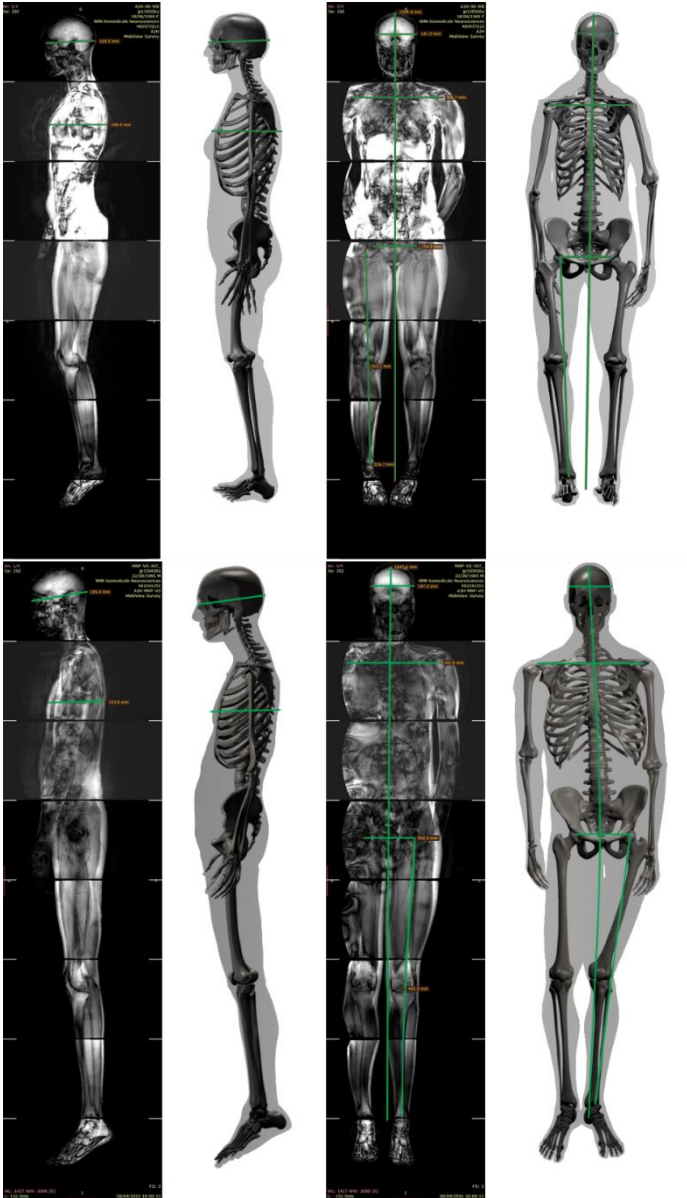
### Different types of anatomical bones :

- **Short bones:** 1 frame in the middle
- **Long bones:** 2 frames, one at each bone head
- **Flat bones:** 3 frames equally placed
- **Complex bones:** 3-4 frames equally placed
- **Complete skull:** 5 frames equally placed

Internal Anatomy Registration: with anatomical constraints



Laplacian interpolation







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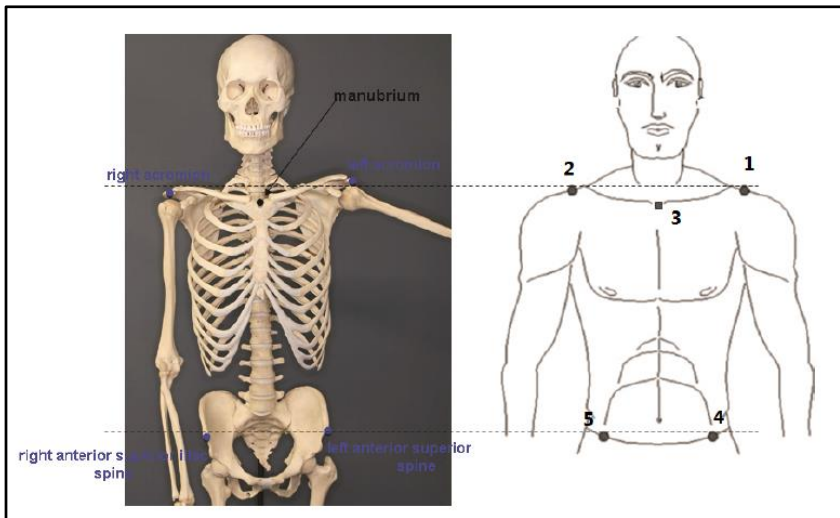
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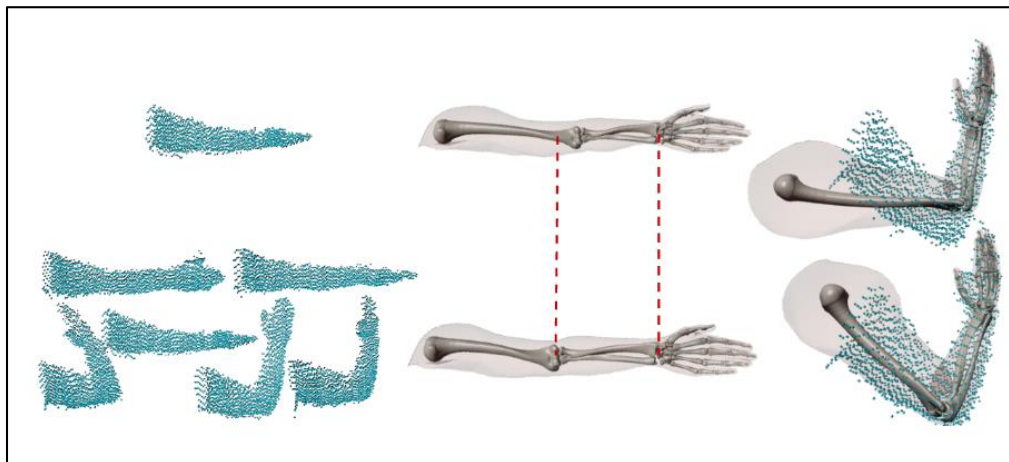
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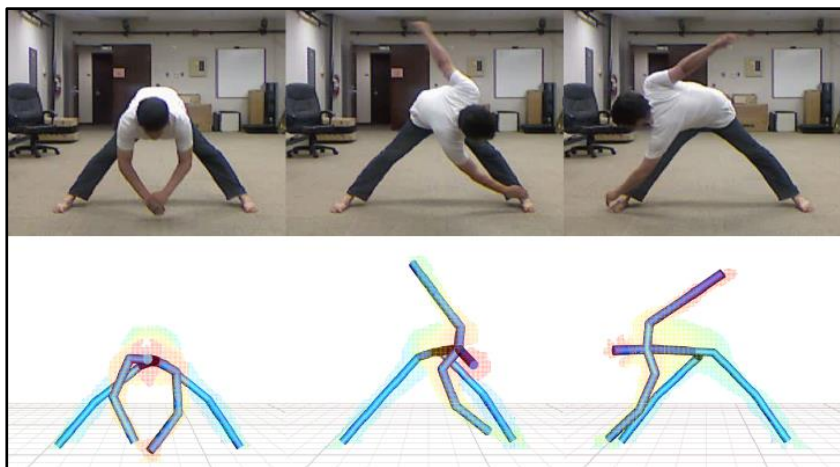
# User tracking : state of the art



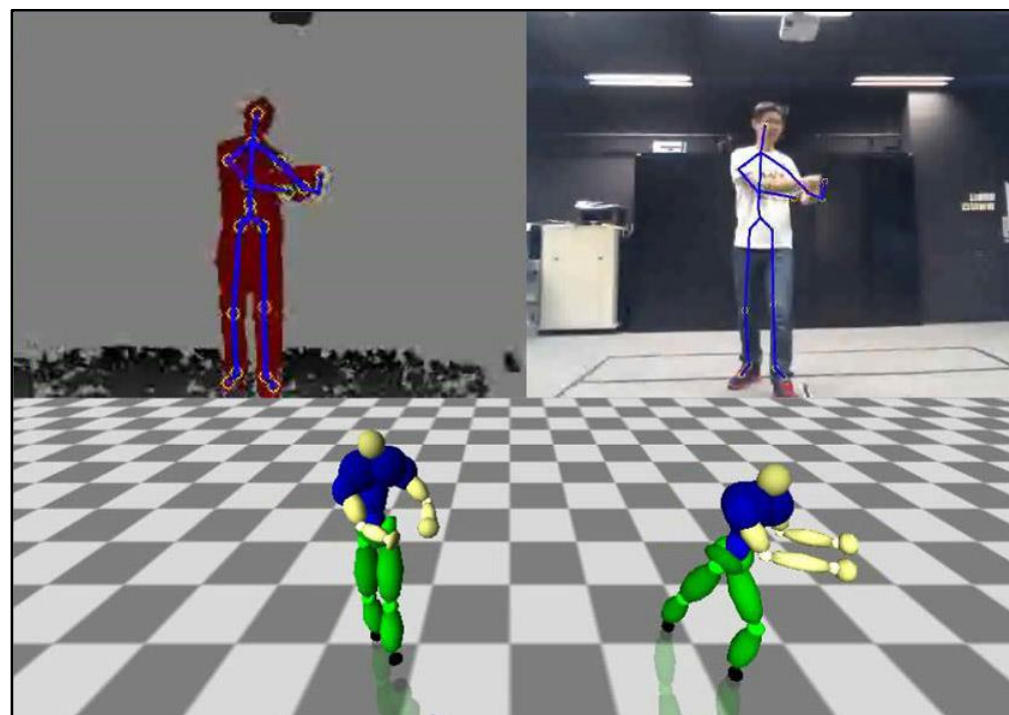
> Meng et al [2013]



> Zhu et al [2015]



> Wei et al [2012]



> Zhou et al [2014]

# Our method : tracking pipeline

Real-time Motion using a commodity depth camera

Input : **Body tracking skeleton**

*(25 joints positions)*

Smoothing of small tracking noise  
*(Kalman filter on positions)*

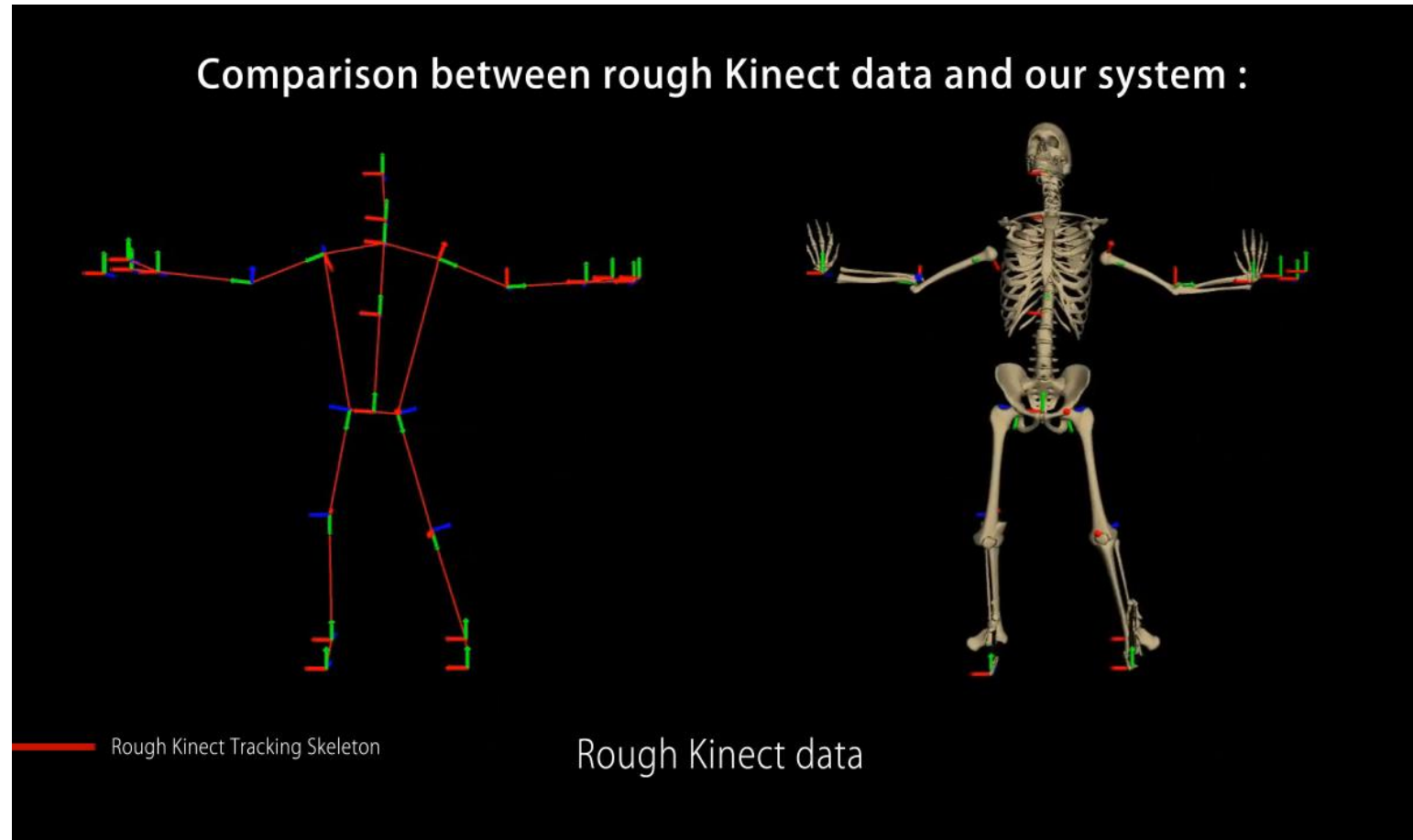
Hierarchical body tracking system  
*(in-between joint distances)*

Anatomically constrained joint Orientations  
*(dofs and angle limits)*

Output : **Realistic body tracking**

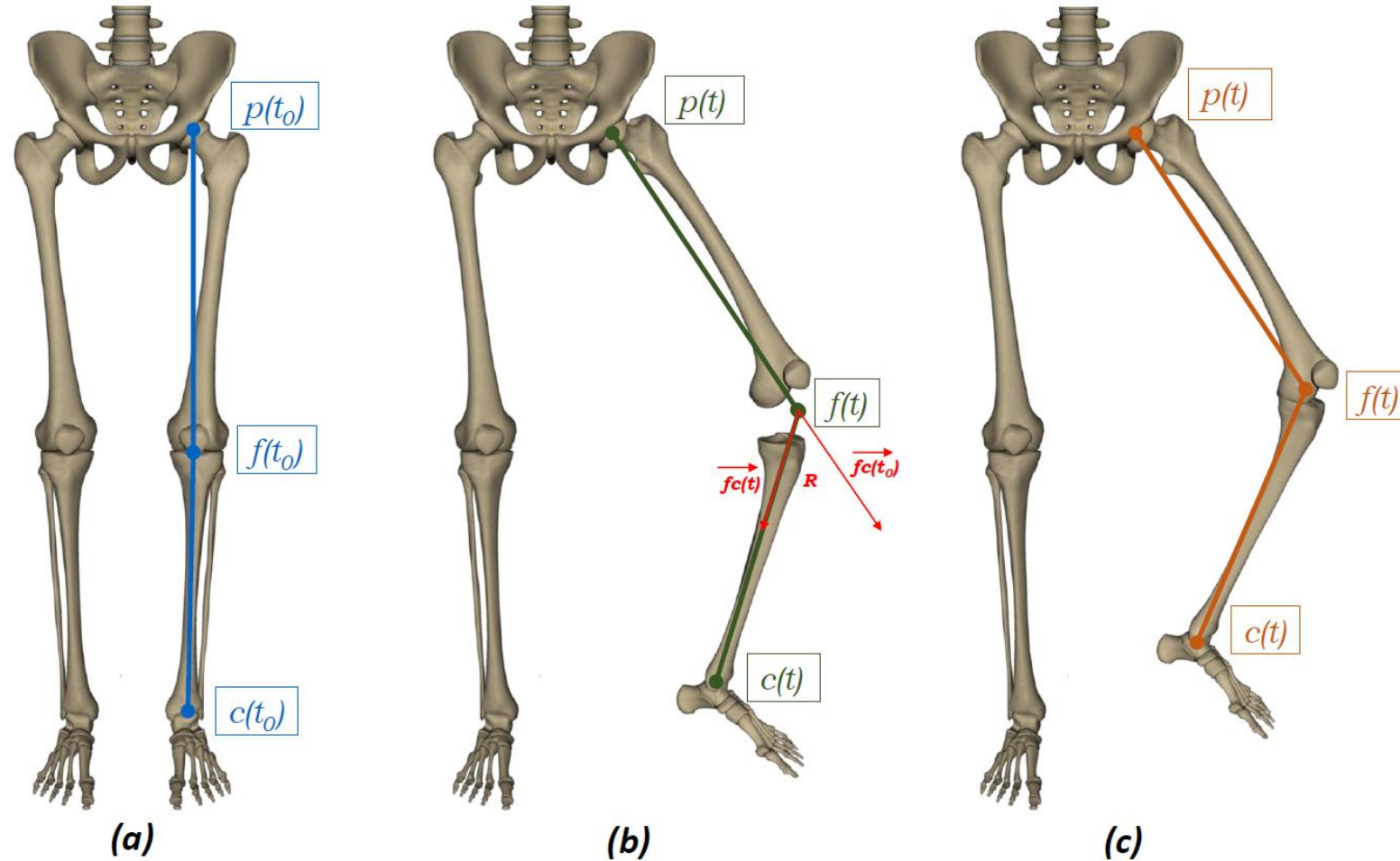
*(body joints position and orientations)*

Comparison between rough Kinect data and our system :





# Hierarchical body tracking

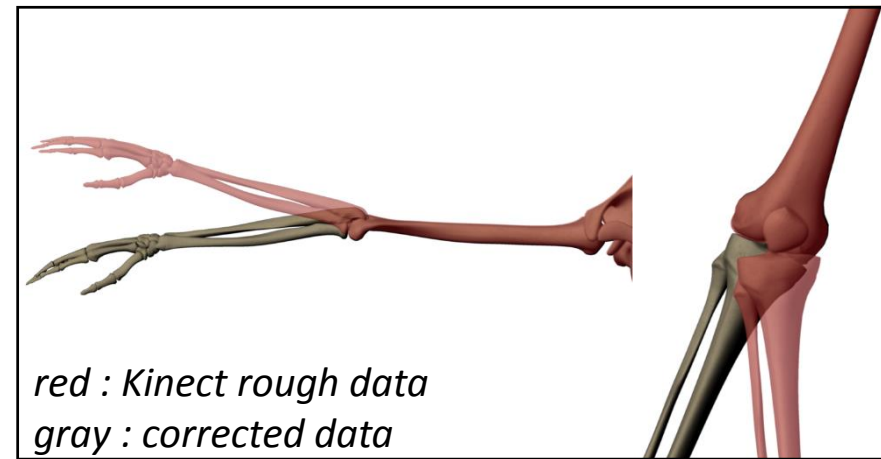


- (a):** our hierarchical body tracking skeleton at (t<sub>0</sub>).
- (b):** Kinect body tracking skeleton at (t).
- (c):** our result.

The 3x3 rotation matrix R :

$$\alpha = \text{asin} \left( \left\| \vec{f_c}(t_0) \wedge \vec{f_c}(t) \right\| \right)$$
$$\text{axis} = \frac{\left( \vec{f_c}(t_0) \wedge \vec{f_c}(t) \right)}{\left\| \vec{f_c}(t_0) \wedge \vec{f_c}(t) \right\|}$$

Anatomical constrained joint orientations :



red : Kinect rough data  
gray : corrected data

To evaluate the quality of our mirror-like AR system.

	C01	C02	C03	C04	C05	C06
bad (--)	0	3	1	0	0	2
average (-+)	4	10	6	2	2	5
good (++)	16	7	13	18	18	13

The user study group is composed of :

- 13 men between 24 and 54 years old  
(average height: 181cm, average weight: 82.6kg)
- 7 women between 22 and 44 years old  
(average height: 164cm, average weight: 61.7kg)

**(C01) Body position range**

*motions while standing, crouching or sitting.*

**(C02) Body orientation range**

*body orientation from Kinect point of view: facing, profile, 3/4, back.*

**(C03) Motion range**

- *simple motions like Flexion/extension of the knee*
- *complex motions in the extremities (finger motion, etc.)*

**(C04) Motion fluidity and delay**

**(C05) Motion consistency**

*absence of outliers during motion.*

**(C06) Motion plausibility**

*joint DOFs and angular limits.*



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# Our results



> Required Motion



> Fitness Motion



> Extreme Motion



> Free Motion

Thanks to the use of **anatomical knowledge**, we significantly **improve AR realism** and **anatomy motion plausibility** with respect to our previous works in the Living Book of Anatomy project.

## Future Work :

- Silhouette retargeting : to ensure that the 3D user-specific data always lies within it
- Biomechanical simulation : for more realistic soft tissues deformations
- Inverse Dynamics : for full body muscular activity

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### Living Book of Anatomy (LBA) Project : See your Insides in Motion!

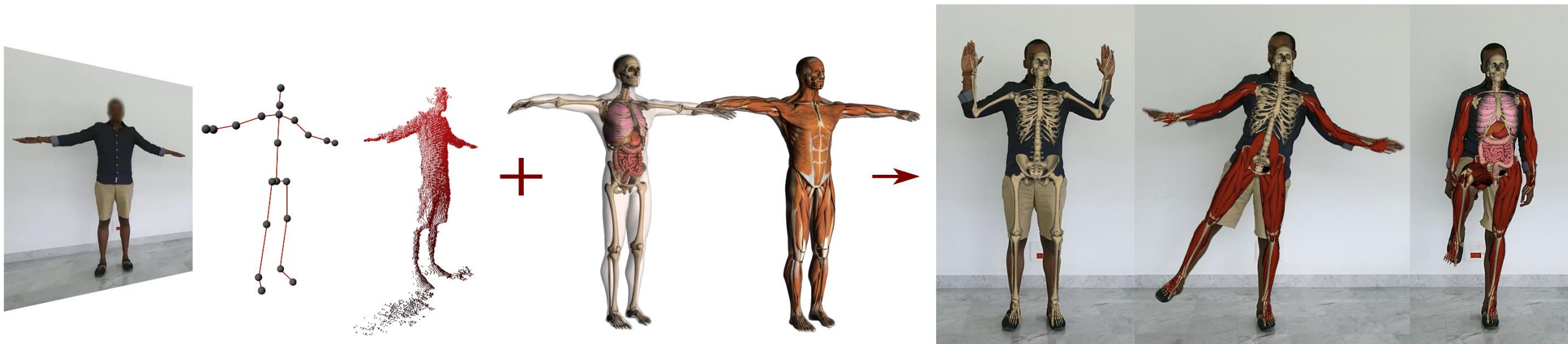
Armelle Bauer, Ali-Hamadi Dicko, Olivier Palombi, François Faure, Jocelyne Troccaz  
Emerging Technologies – Siggraph Asia, **2015**

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### Interactive Visualization of Muscle Activity During Limb Movements : Towards Enhanced Anatomy Learning

Armelle Bauer, Florent Paclet, Violaine Cahouet, Ali-Hamadi Dicko, Olivier Palombi, François Faure, Jocelyne Troccaz  
Eurographics Workshop on Visual Computing for Biology and Medicine (VCBM), **2014**

## Anatomical Mirroring: Real-time User-specific Anatomy in Motion Using a Commodity Depth Camera.



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<sup>1</sup> LADAF, <sup>2</sup> LJK, <sup>3</sup> TIMC-IMAG, <sup>4</sup> AnatoScope — **INRIA, CNRS, Univ. Grenoble Alpes**